

Manipulator Specification Worksheet

| MOUNTING FLANGE | Size (CF): | |
|----------------------------|---|--|
| | Bolt Hole Type: | |
| MANIPULATOR ORIENTATION | VERTICAL HORIZONTAL INVERTED OTHER Payload Weight: (Required for horizontal mount) | |
| MOTOR CONTROLLER | Yes O No O | |
| Z-AXIS: | (Specifyin 1" increments) Resolution: | |
| Z-AXIS CONTROL: | Manual Knob Adjust 🗖 or Motor Drive 🗖 Limits 🗖 Encoder: None 🗖 Rotary 🗖 or Linear 🗖 Encoder Resolution: | |
| X-Y AXES: | $\pm 0.5" \square \pm 1.0" \square$ Resolution: | |
| X-Y AXES CONTROL: | Manual Micrometer Adjust 🗖 or Motor Drive 🗖 Limits 🗖 Encoder: None 🗖 Rotary 🗖 or Linear 🗖 Encoder Resolution: | |
| POLAR ROTATION: | ±° Resolution: | |
| POLAR ROTATION | Manual or MotorDrive | |
| CONTROL: | Limits | |
| EncoderNone Rotary | | |
| Encoder Resolution: | | |

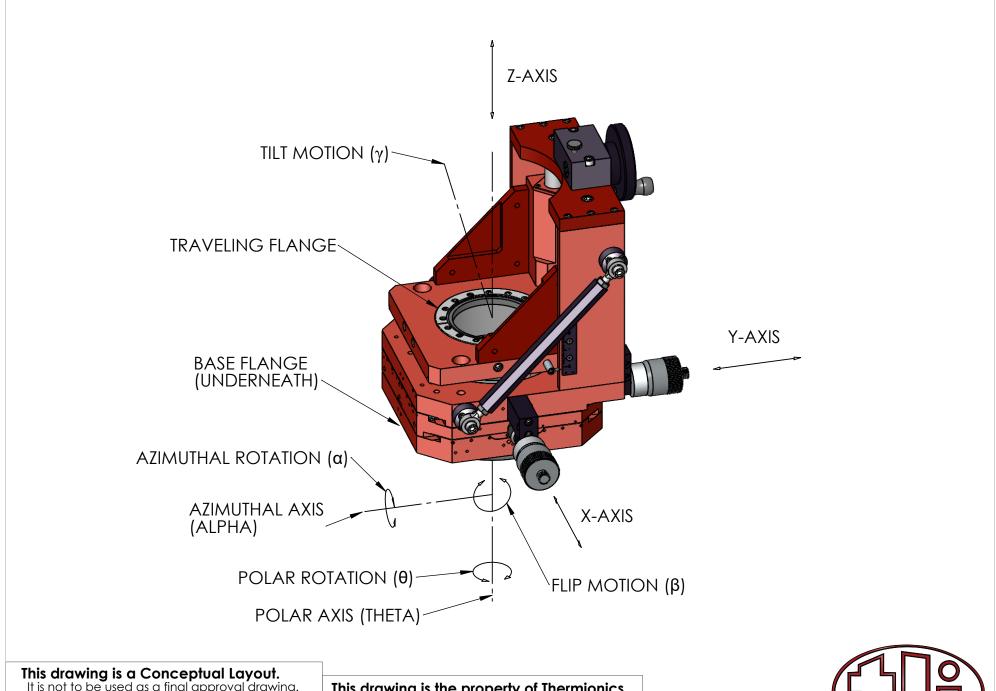
If incorporating a sample, continue to page 2.

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Heating and cooling notes: Specifications are estimates. Temperatures quoted refer to <u>face of sample</u> <u>platen</u>; actual <u>sample</u> temperature depends on many factors including but not limited to size, thickness, emissivity, cooling, and attachment methods.

| SAMPLE ORIENTATION: | Sample axis in-line 🗖 |
|---|--|
| | Perpendicular to Z axis 🗖 Other: |
| SAMPLE AZIMUTHAL ROTATION: | ±° Resolution: |
| SAMPLEAZIMUTHAL | Manual 🗖 or Motor Drive 🗖 |
| ROTATION CONTROL: | Limits 🗖 |
| | Encoder: None 🗖 Rotary 🗖 |
| | Encoder Resolution: |
| SAMPLEFLIP MOTION: | ±° Resolution: |
| SAMPLE FLIP CONTROL: | Manual 🗖 or Motor Drive 🗖 |
| | Limits 🗖 |
| | Encoder: None 🗖 Rotary 🗖 |
| | Encoder Resolution: |
| SIZE OF SAMPLE/WAFER: | Size and Shape: |
| SAMPLE THICKNESS: | |
| (Required if offset is critical) | |
| SAMPLE OFFSET: | |
| SAMPLE HEATING: | |
| (Specifyin °C, cont., max. & duration) | |
| SAMPLE COOLING: | |
| (Specify in °C) | |
| SAMPLE PLATEN STYLE: | STLC 🗖 (with TTC, LR, HRD options if known) |
| | SPF |
| | Other 🗖 Materials: |
| SAMPLE PLATEN ELECTRICAL: | Fully Isolated 🗖 |
| (CHOOSE ONE) | (default, floating, can build up static charge) |
| | Grounded 🗖 |
| | (sample platen grounded through system components) |
| | Selective Isolation |
| | (incorporates BNC feedthrough to isolate, ground, or connect |
| | meter to read current) |
| | Biased 🗖 |
| | (applied voltage, must be specified to design spark gaps and |
| | provide correct feedthroughs) |
| IN-VACUUM SAMPLE TRANSFER: | Yes O No O |
| IN-VACUUM WIRING INSULATION: | Ceramic Beads 🛛 or Kapton® coated 🗖 |
| REDUCED MAGNETIC PERMEABILITY: | |
| REDUCED MAGNETIC PERMEABILITY. | If yes, Gauss level at measured distance from sample: |
| | n yes, Gaussieveral measured distance normsample. |
| VACUUM ENVIRONMENT / | Chamber base pressure: |
| PRESSURE:) | Highest operating pressure: |
| PRESSURE.) | Gasses and partial pressures REQUIRED if applicable: |
| | Gasses and partial pressures REQUIRED II applicable. |
| HEATER POWER SUPPLY: | Yes O No O |
| | |
| MAXIMUM BAKE OUT TEMPERATURE: | |
| (RNN™ rotary seal is limited to 150° C, | |
| all other limits are 200° C) | |
| OTHER: | |
| | |
| | |

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This drawing is a Conceptual Layout. It is not to be used as a final approval drawing. Some components may not be to scale or may depict features which have not been purchased with this project. Final approval drawings may be available prior to manufacturing.

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